

A Monte Carlo approach for efficient estimation of extreme response statistics

A. Naess^{1,2)} and O. Gaidai¹⁾

¹⁾Centre for Ships and Ocean Structures

²⁾Department of Mathematical Sciences

Norwegian University of Science and Technology

Trondheim, Norway

Introduction

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- Recent years have seen the appearance of importance sampling techniques also for dynamical systems, but these are fairly involved and are not likely to become widely used in practical applications.
- Are standard Monte Carlo methods really useless in this context?
- NOT QUITE!

The Response Process

- The equations of motion for the dynamic system considered is assumed to be of the form

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\mathbf{M} denotes a generalized $n \times n$ mass matrix,

$\mathbf{X} = \mathbf{X}(t) = (X_1(t), \dots, X_n(t))^T$ = the system response vector,

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$\mathbf{F}(t)$ denotes a stochastic loading process.

- Hence the solution $\mathbf{X}(t)$ is also a stochastic vector process.
- For specific prediction purposes, it is usually the extreme values of one, or possibly a combination of several, of the component processes of $\mathbf{X}(t)$ that is sought. For simplicity, denote it by $X(t)$.

The Mean Upcrossing Rate

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Under suitable regularity conditions on the response process the following formula obtains

$$\nu^+(\xi; t) = \lim_{\Delta t \rightarrow 0} \frac{E[N^+(\xi; t - \Delta t/2, t + \Delta t/2)]}{\Delta t} = \int_0^{\infty} s f_{X(t)\dot{X}(t)}(\xi, s) ds$$

where $f_{X(t)\dot{X}(t)}(\cdot, \cdot)$ denotes the joint PDF of $X(t)$ and $\dot{X}(t) = dX(t)/dt$.

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$$\nu^+(\xi; t) = \int_0^{\infty} s f_{\dot{X}(t)|X(t)}(s|\xi) ds f_{X(t)}(\xi) = E[\dot{X}(t)^+ | X(t) = \xi] f_{X(t)}(\xi),$$

where $\dot{X}^+ = \max(\dot{X}, 0)$.

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Note that the parameter of the Poisson distribution is

$$E[N^+(\xi; 0, T)] = \int_0^T \nu^+(\xi; t) dt.$$

The Mean Upcrossing Rate

It is expedient to rewrite the extreme value distribution as

$$F_{M(T)}(\xi) = \text{Prob}(M(T) \leq \xi) = \exp \left\{ -\bar{\nu}^+(\xi) T \right\},$$

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The averaged mean upcrossing rate $\bar{\nu}^+(\xi)$ is conveniently estimated from simulated response time histories.

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For a suitable number k , e.g. $k \geq 20 - 30$, a good approximation of the 95 % confidence interval for the value $\bar{\nu}^+(\xi)$ is

$$\text{conf. band}(\xi) = \hat{\bar{\nu}}^+(\xi) \pm 1.96 \hat{s}(\xi) / \sqrt{k}$$

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The empirical standard deviation $\hat{s}(\xi)$ is given as

$$\hat{s}(\xi)^2 = \frac{1}{k-1} \sum_{j=1}^k \left(\frac{n_j^+(\xi; 0, T)}{T} - \hat{\bar{\nu}}^+(\xi) \right)^2$$

Mean Upcrossing Rate versus PDF - stationary case

- The PDF $f_X(x)$ of $X(t)$ is written as

$$f_X(x) = \exp \{-\alpha(x)\},$$

where $\alpha(x)$ = a well-behaved function that is strictly increasing for increasing x for $x \geq x_0$ for some x_0 .

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- Now we can write

$$\nu_X^+(x) = q \exp \{-\alpha(x) + \delta(x)\},$$

where $q = \mathbf{E}[\dot{X}^+]$, $\exp \{\delta(x)\} = \mathbf{E}[\dot{X}^+ | X = x] / \mathbf{E}[\dot{X}^+]$.

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- $q \exp \{-\alpha(x)\} = q f_X(x)$ expresses the mean upcrossing rate for the case with independent $X(t)$ and $\dot{X}(t)$.

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- Plotting $\ln \nu_X^+(x)$ versus $\ln f_X(x)$ will then clearly show to what extent $|\delta(x)|$ is dominated by $\alpha(x)$ as $x \rightarrow \infty$.

Extrapolation of Mean Upcrossing Rate

- Assumption:

$$\alpha(x) = a(x - b)^c - d(x), \quad x \geq x_0,$$

where a , b and c are suitable constants, and $d(x)$ is a function of much slower increase than $\alpha(x)$.

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- Hence, we assume that

$$\nu_X^+(x) = \tilde{q}(x) \exp\{-a(x - b)^c\}, \quad x \geq x_0,$$

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- The particular choice for the function $\alpha(x)$ reflects the basic assumption of an asymptotic Gumbel distribution of the extremes.

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- It follows that

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- Choice of initial value \tilde{q}_0 for $\tilde{q}(x)$ would be based on looking at the ratio $\nu_X^+(x) / f_X(x) = \tilde{q}(x) \exp\{-d(x)\}$ for large x .
- Practical solution: $\tilde{q}_0 = \langle \nu_X^+(x) / f_X(x) \rangle$ (tail average), followed by optimization wrt b .

Numerical Examples - Duffing oscillator

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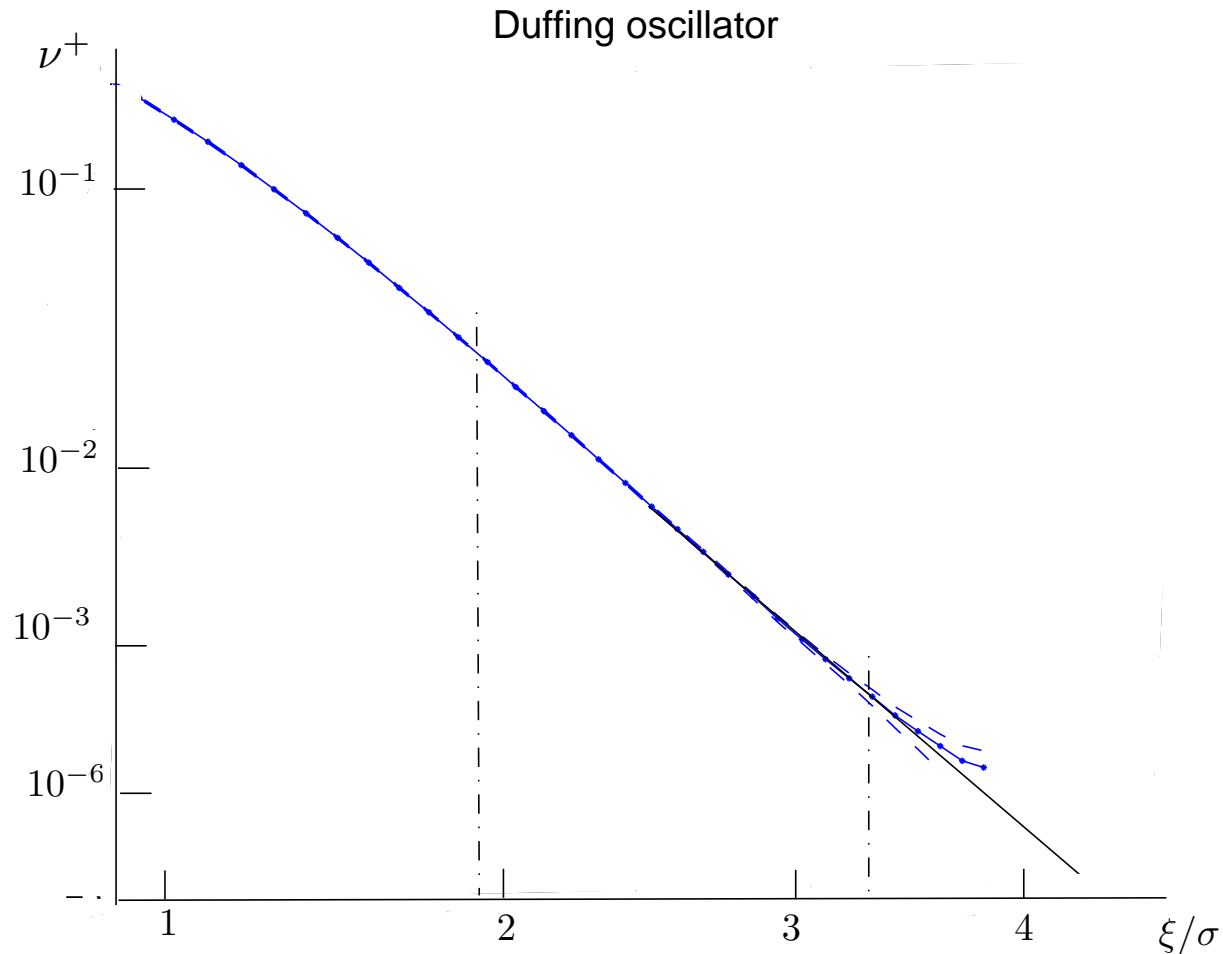
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- $f_{X\dot{X}} = f_X f_{\dot{X}}$ is known in closed form.

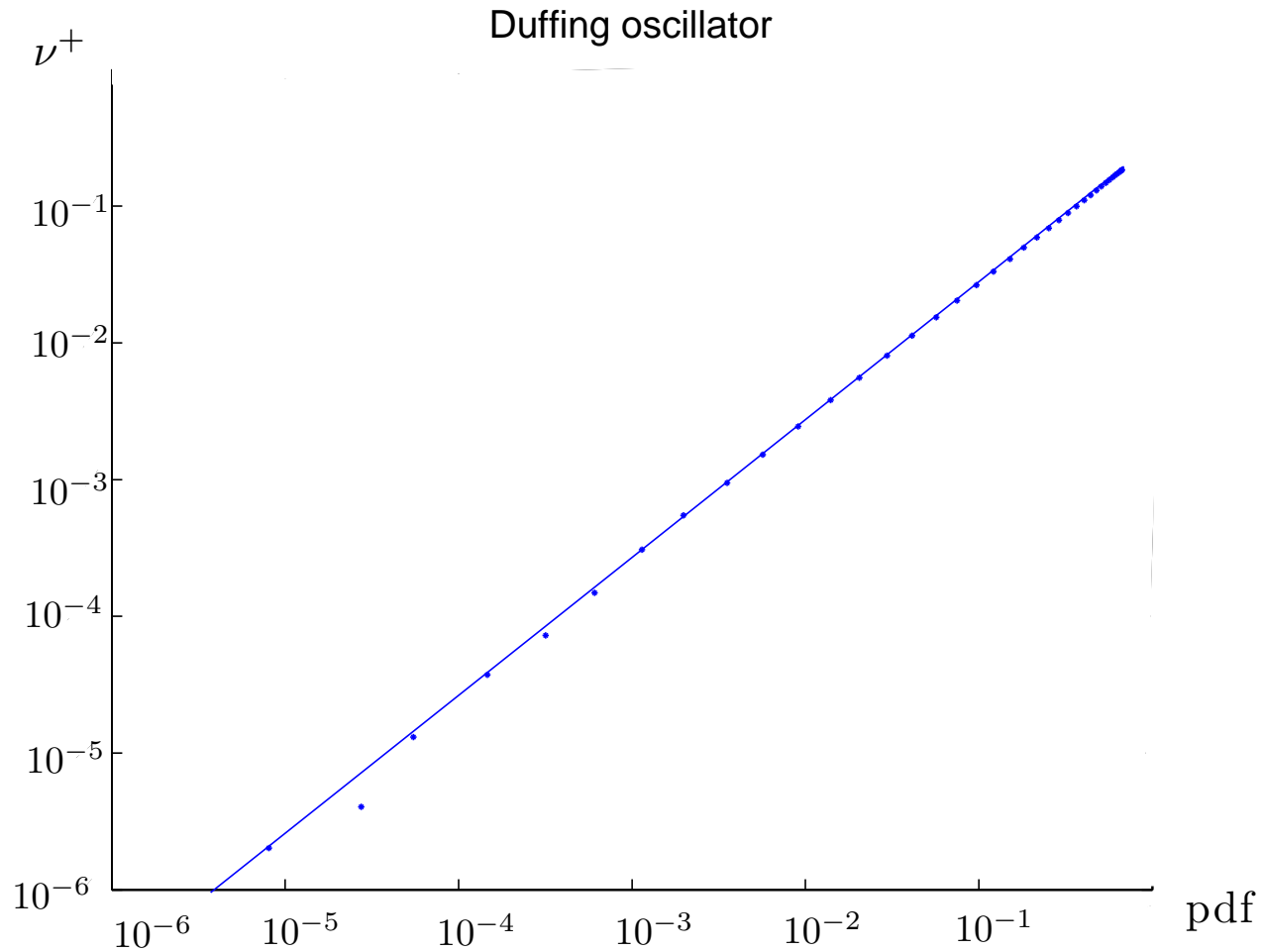
Numerical Examples - Duffing oscillator

Upcrossing rates estimated from Monte Carlo simulations (*) with 95% confidence band (---) versus analytical results (—) for the mean upcrossing rate.



Numerical Examples - Duffing oscillator

Monte Carlo (*) and analytical (—) results the mean upcrossing rate versus PDF on the log scale. Slope = 1.0



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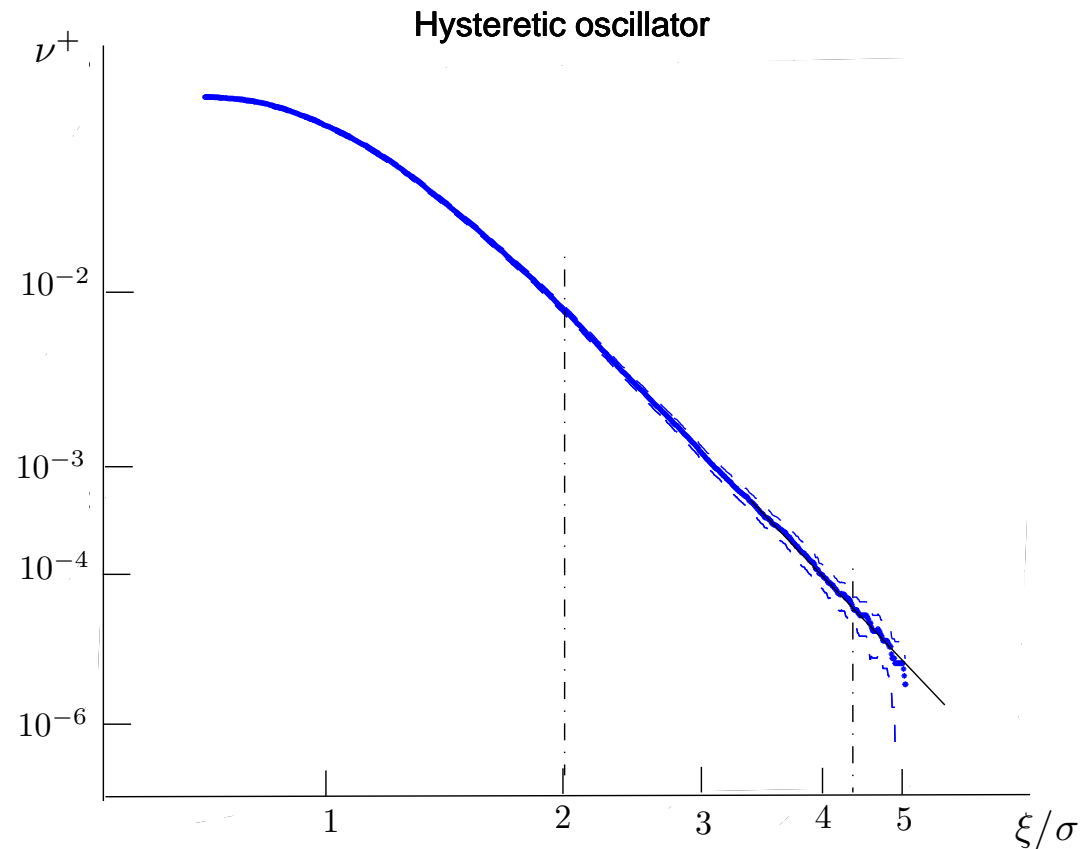
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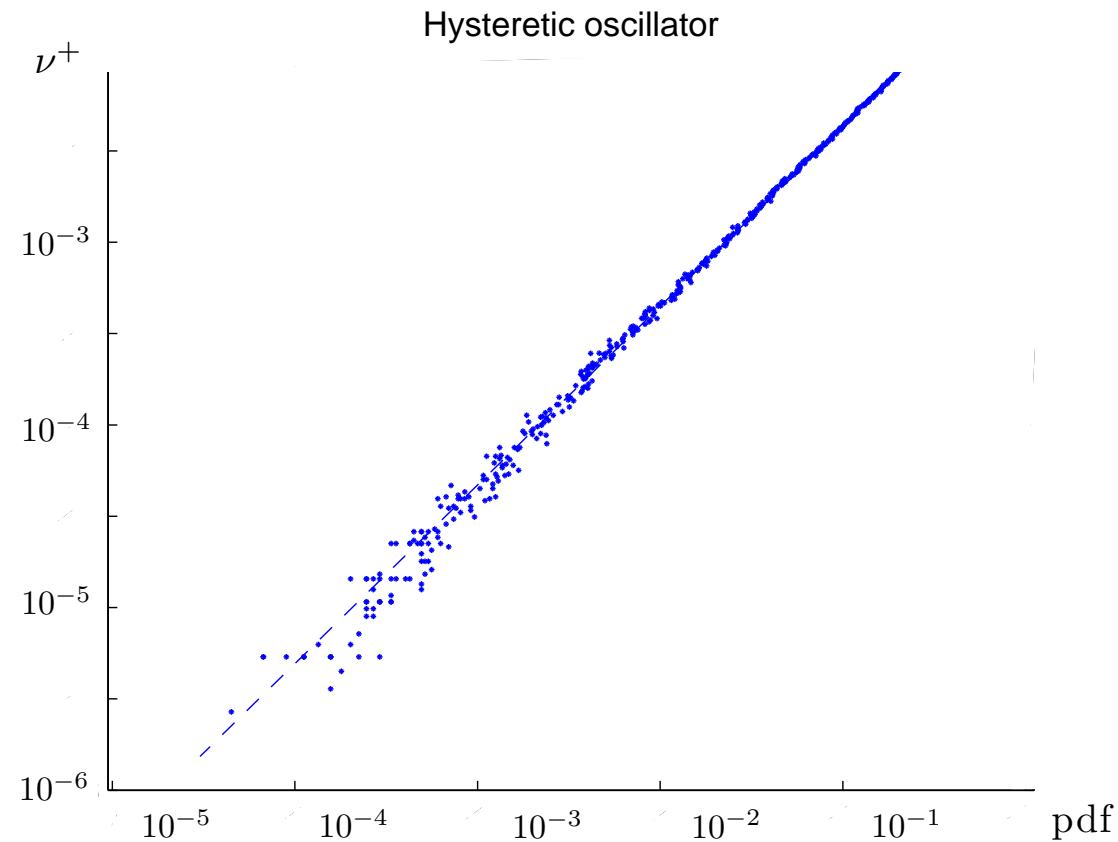
Numerical Examples - Hysteretic oscillator

Monte Carlo results for the mean upcrossing rate, 100 realizations (*) along with 95% confidence bands (---) versus 50000 realizations (—).



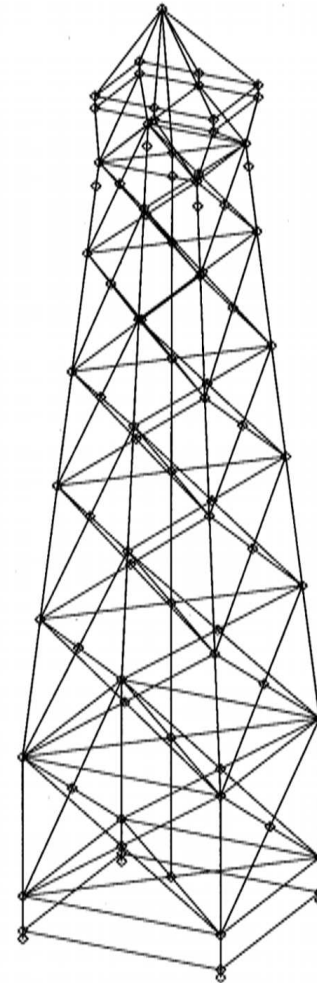
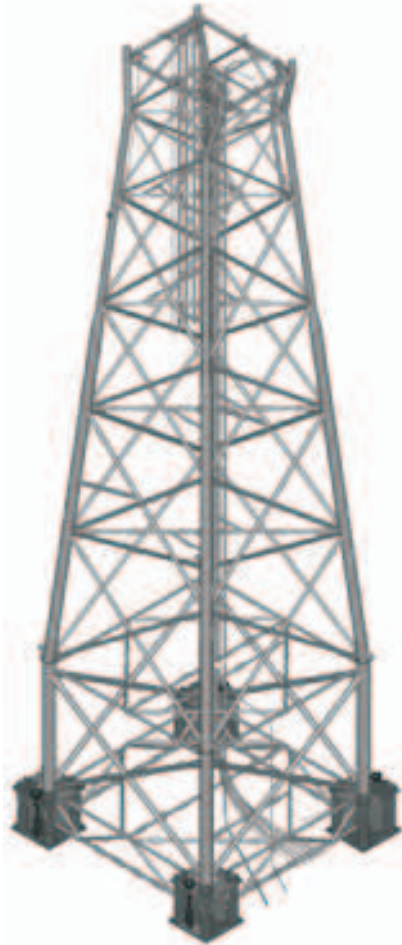
Numerical Examples - Hysteretic oscillator

Monte Carlo results for the mean upcrossing rate versus PDF, 100 realizations (*) versus 50000 realizations (—). Slope = 1.02



Numerical Examples - Jacket structure

The Kvitebjørn jacket platform with the superstructure removed.



Numerical Examples - Jacket structure

- The equation of motion for the horizontal excursions of the jacket at main deck level is

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- $\mathbf{Q} = (Q(t, \mathbf{x}_1), \dots, Q(t, \mathbf{x}_N))^T$, where $Q(t, \mathbf{x}_k) = F_{in}(t, \mathbf{x}_k) + F_d(t, \mathbf{x}_k)$, $k = 1, \dots, N$ and $-d = z_1 \leq z_k \leq z_N = L - d$, where $d = 190$ m is the water depth and $L = 216$ m is the jacket support height.

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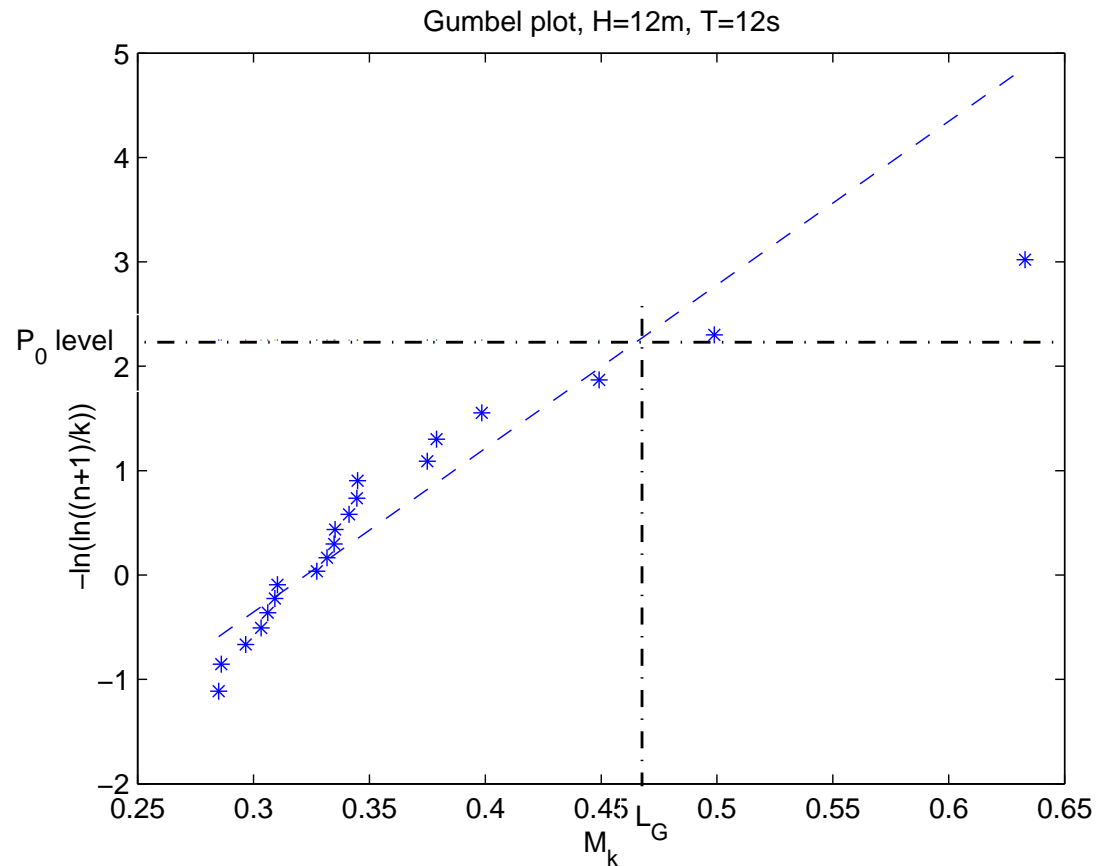
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-

$$k_m = C_m \rho \pi D^2 / 4, \quad k_d = C_d \rho D / 2$$

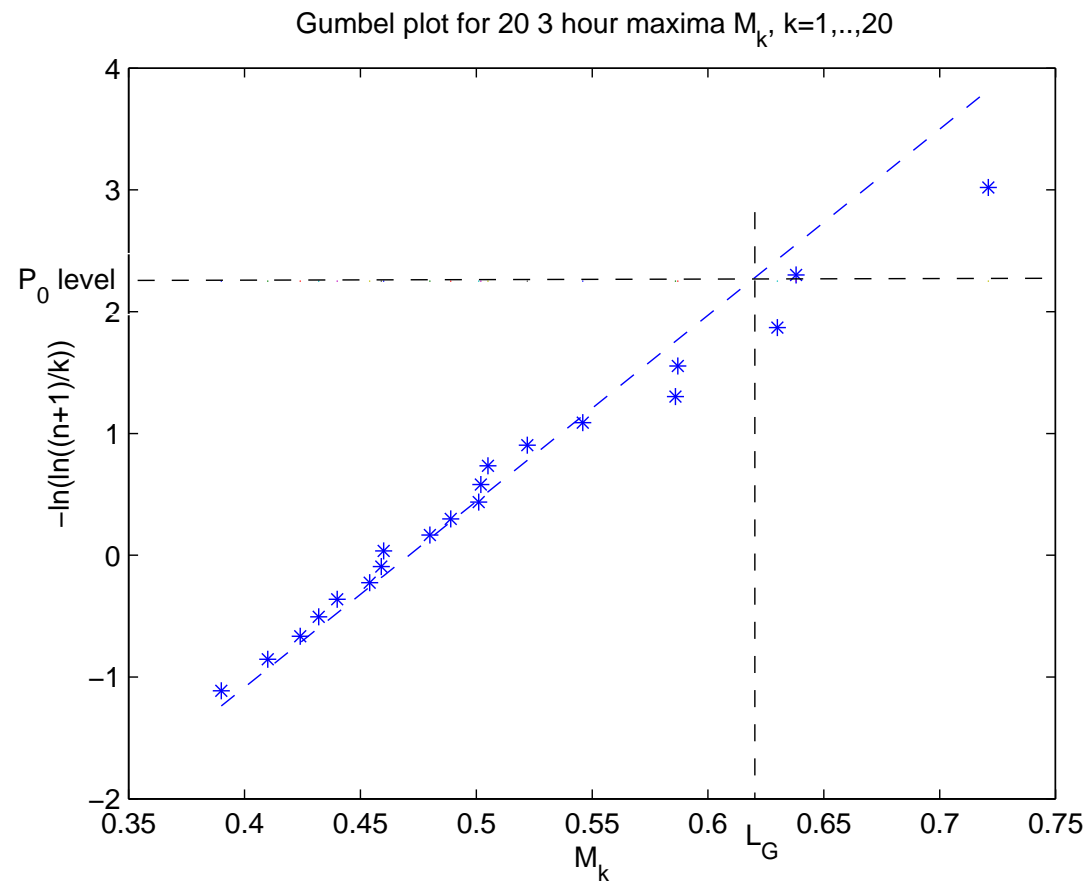
Numerical Examples - Jacket structure

Gumbel plot of 20 simulated 3 hour extremes with fitted Gumbel distribution. Sea state with $H_s = 12$ m, $T_p = 12$ s.



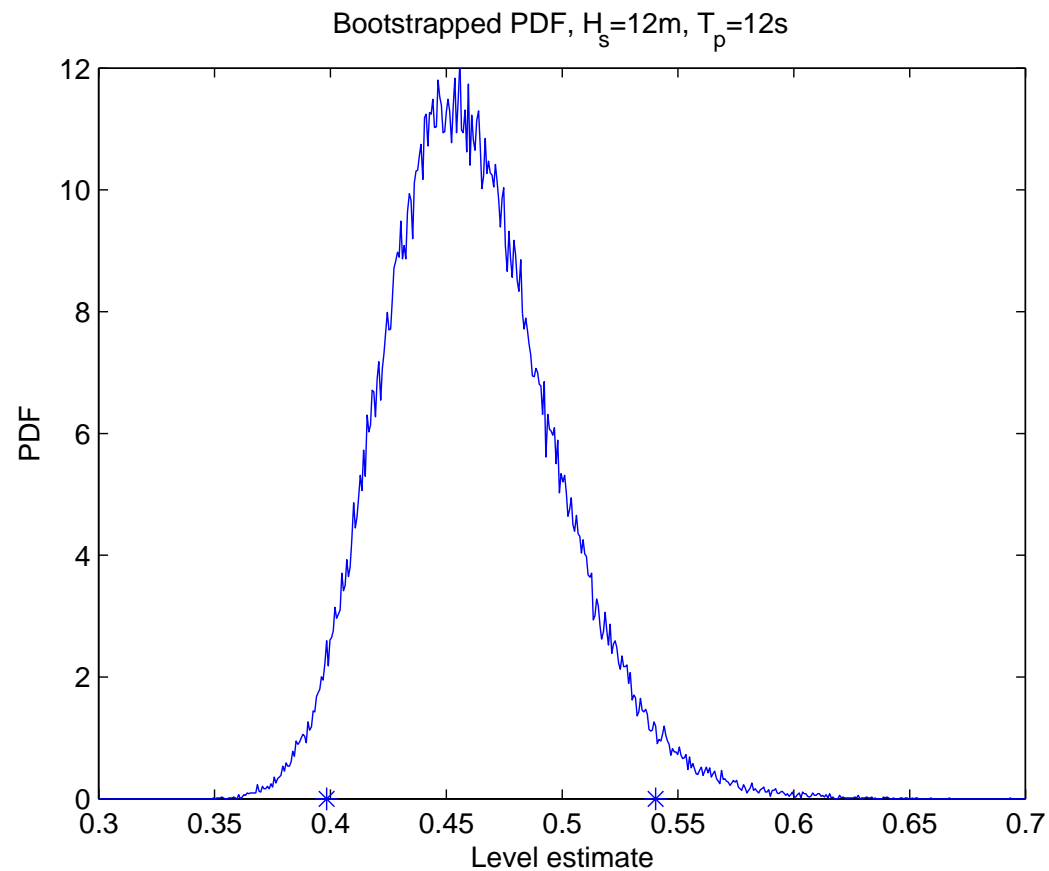
Numerical Examples - Jacket structure

Gumbel plot of 20 simulated 3 hour extremes with fitted Gumbel distribution. Sea state with $H_s = 14.7$ m, $T_p = 15$ s.



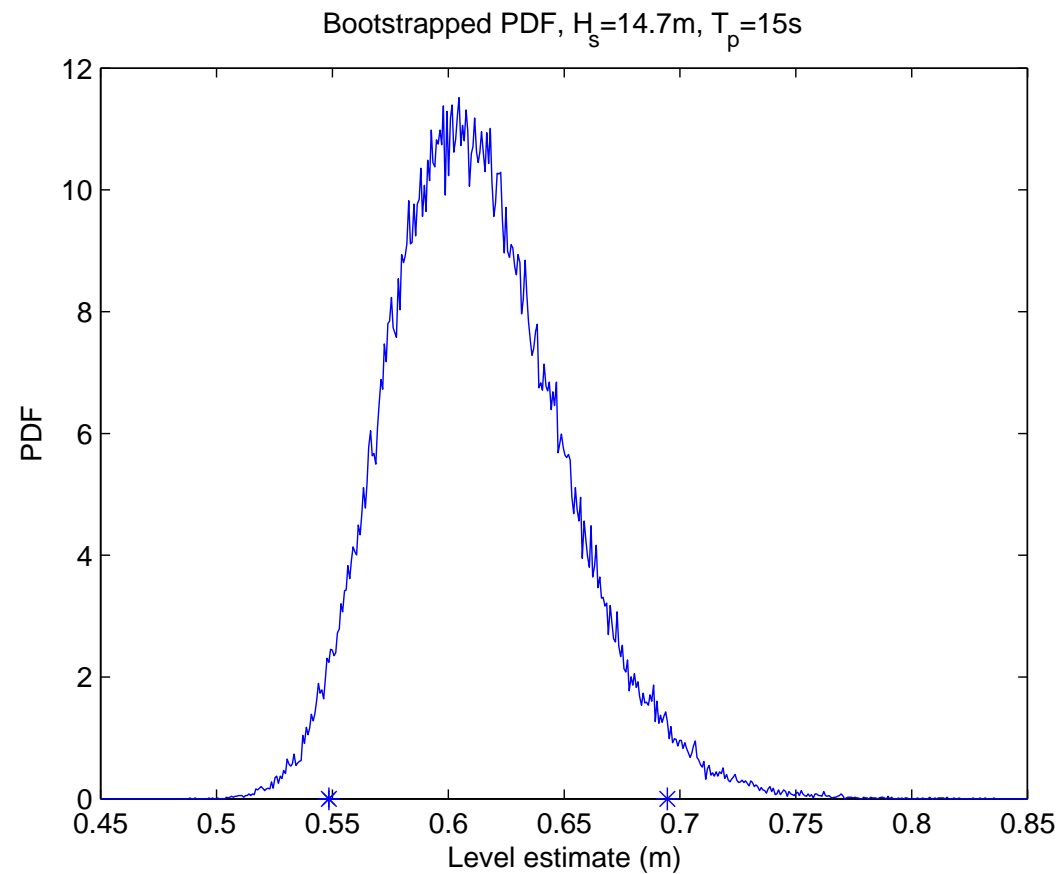
Numerical Examples - Jacket structure

Empirical PDF of the 90% fractile value based on samples of size 20 for the sea state with $H_s = 12$ m, $T_p = 12$ s.



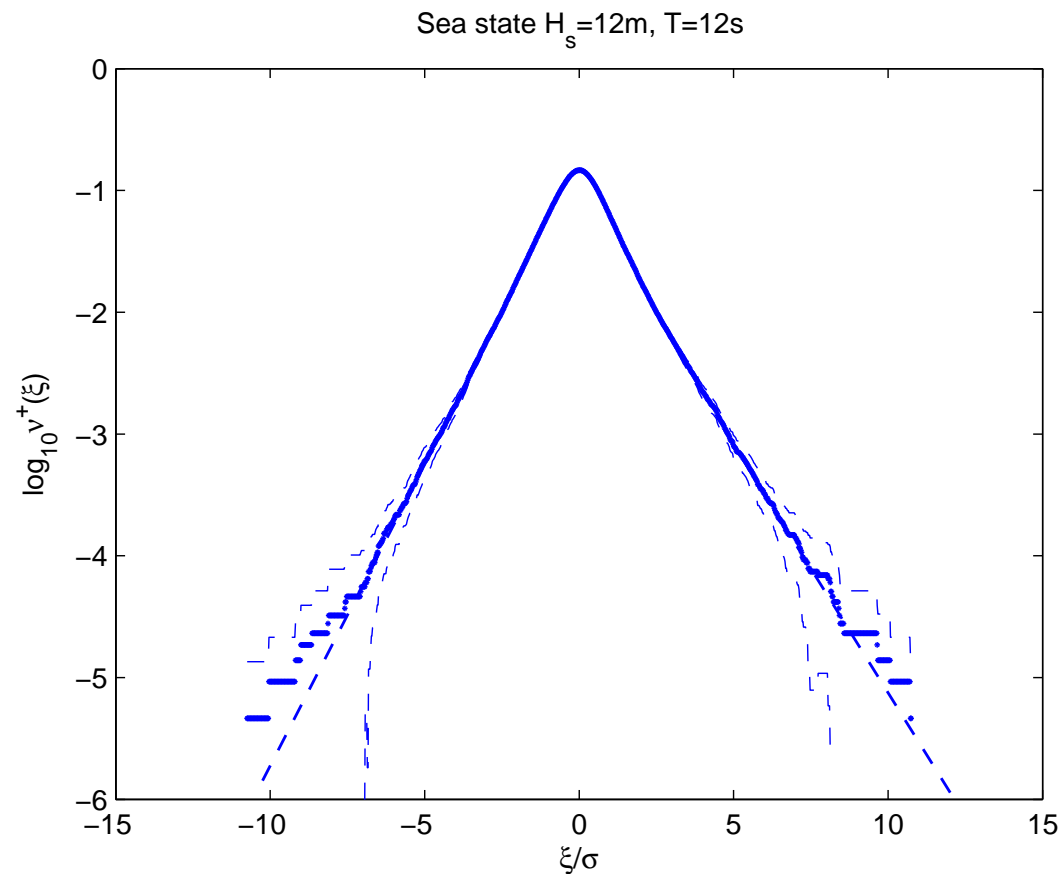
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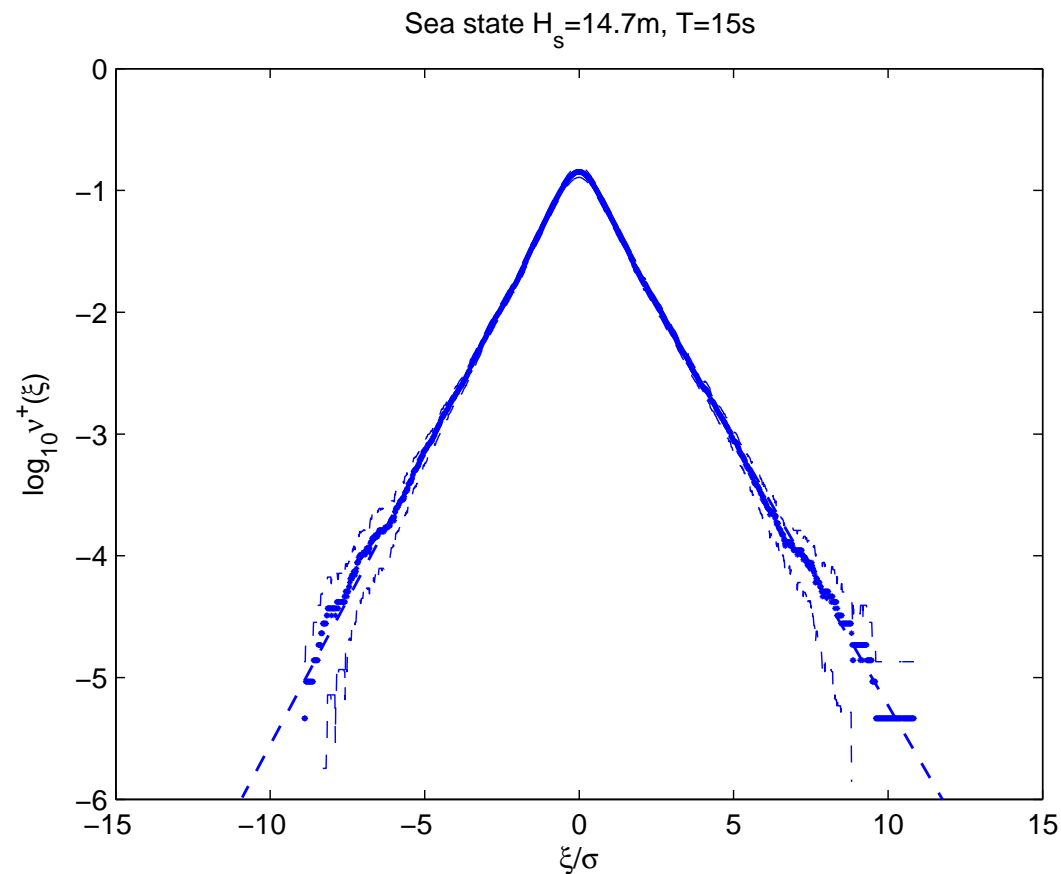
Numerical Examples - Jacket structure

Mean upcrossing rate statistics along with 95% confidence bands (---) for the sea state with $H_s = 12$ m, $T_p = 12$ s, $\sigma = 0.047$ m. * : Monte Carlo; - - - : linear fit.



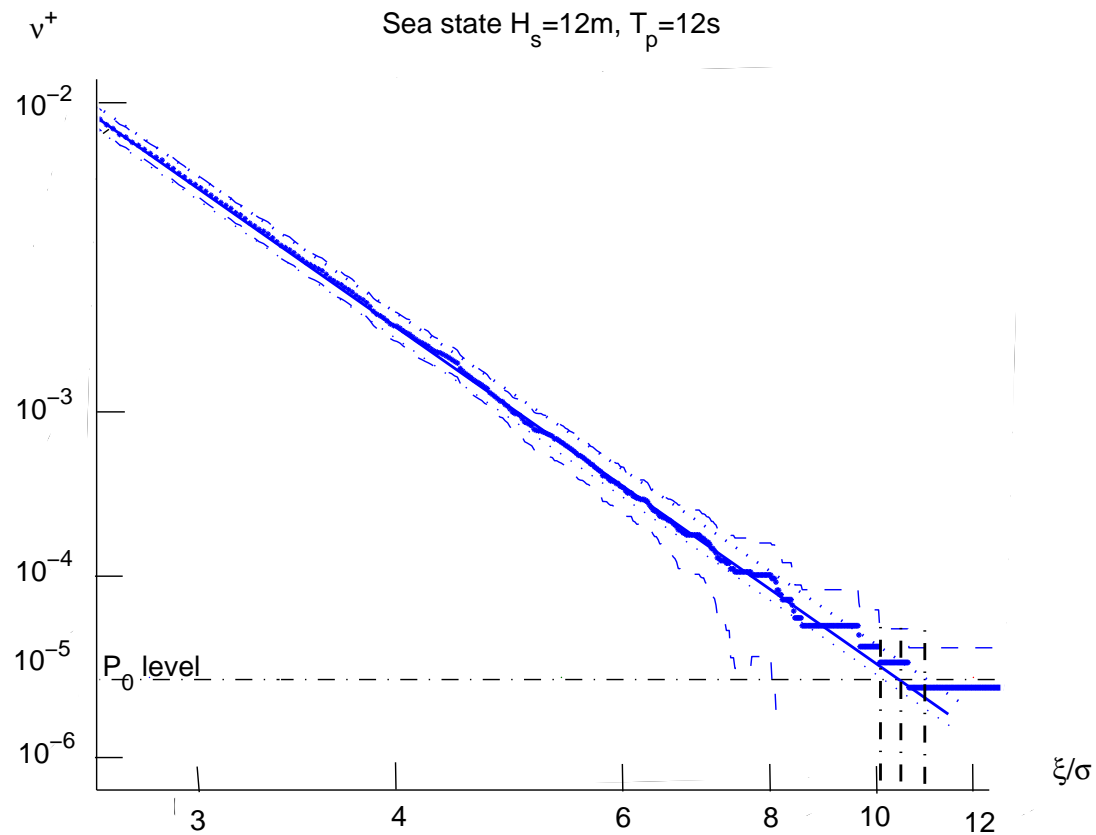
Numerical Examples - Jacket structure

Mean upcrossing rate statistics along with 95% confidence bands (---) for the sea state with $H_s = 14.7$ m, $T_p = 15$ s, $\sigma = 0.066$ m. * : Monte Carlo; - - - : linear fit.



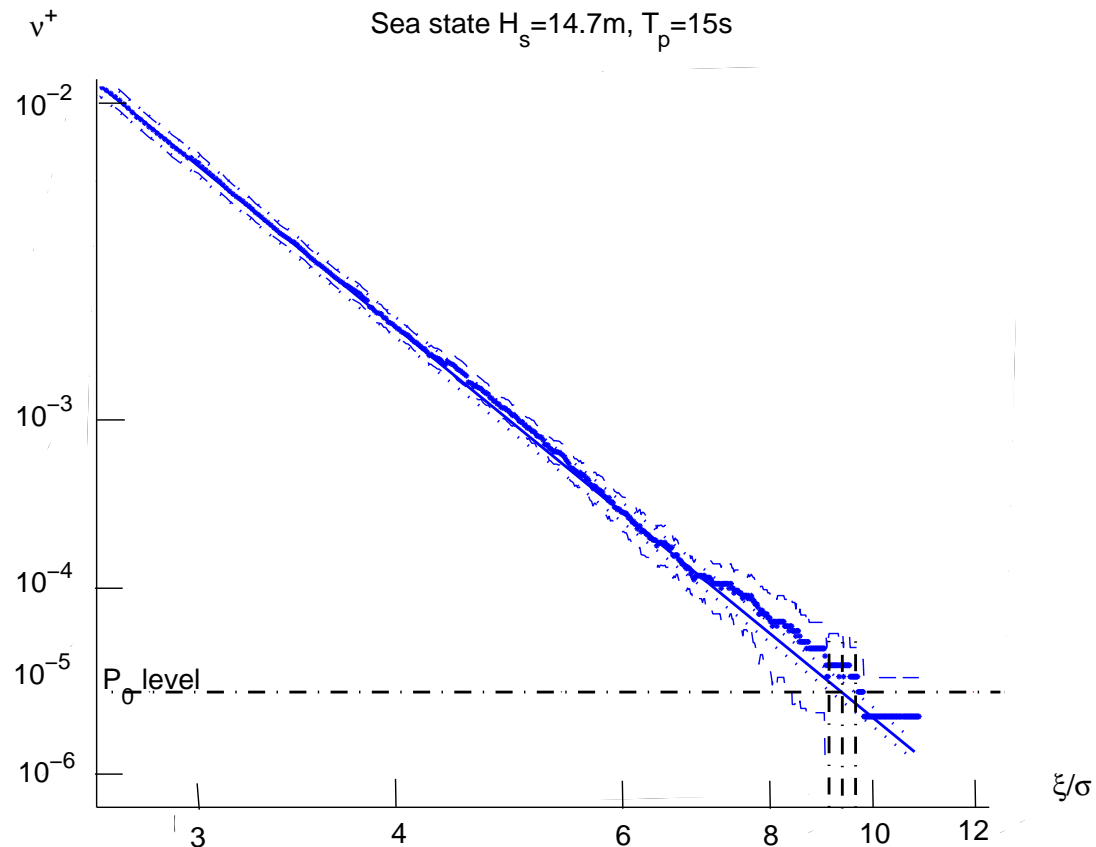
Numerical Examples - Jacket structure

Transformed plot along with 95% confidence bands (---) for the sea state with $H_s = 12$ m, $T_p = 12$ s, $\sigma = 0.047$ m. * : Monte Carlo; — : linear fit, $q = 0.04$, $b = 1.4\sigma$.



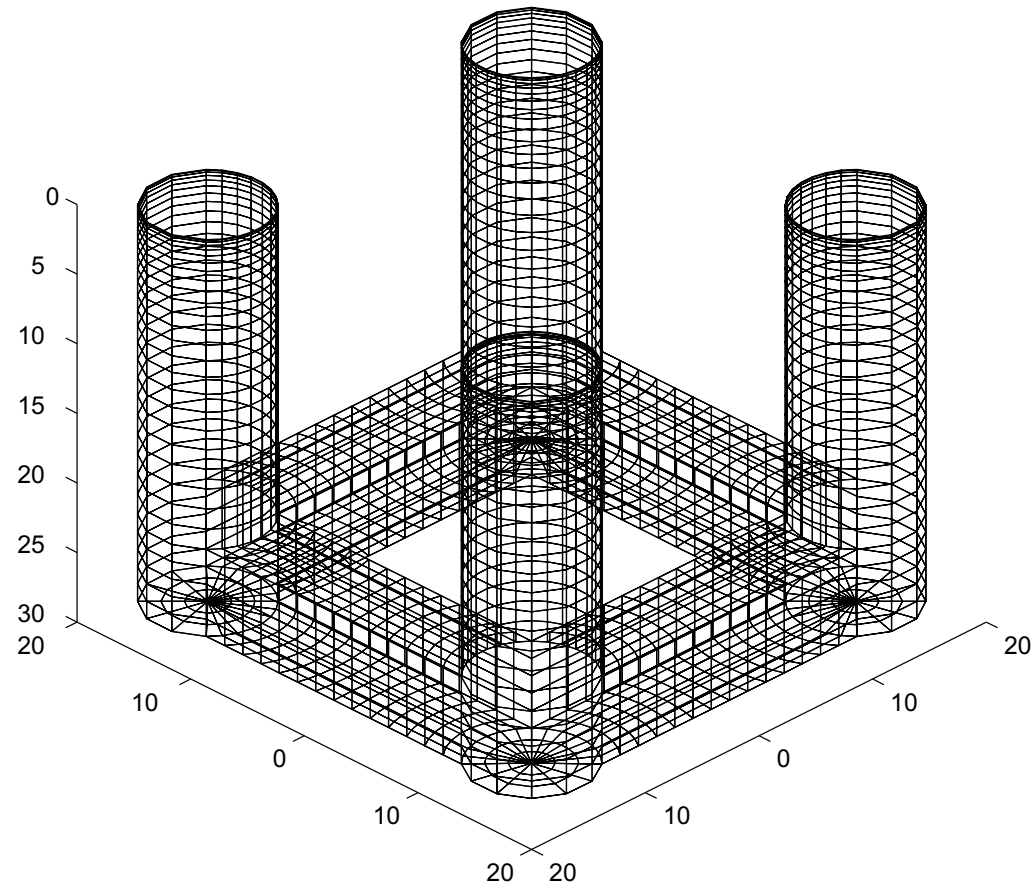
Numerical Examples - Jacket structure

Transformed plot along with 95% confidence bands (—) for the sea state with $H_s = 14.7$ m, $T_p = 15$ s, $\sigma = 0.066$ m. * : Monte Carlo; — : linear fit, $q = 0.06$, $b = 0.9\sigma$.



Numerical Examples - TLP

Sketch of submerged part of TLP.



Numerical Examples - TLP

- The equation of motion for the horizontal excursions of the TLP is

$$\mathbf{M}\ddot{\mathbf{Z}}(t) + \mathbf{D}(t)\dot{\mathbf{Z}}(t) + \mathbf{C}(\dot{\mathbf{Z}}(t)) + \mathbf{K}(\mathbf{Z}(t)) = \mathbf{F}(t)$$

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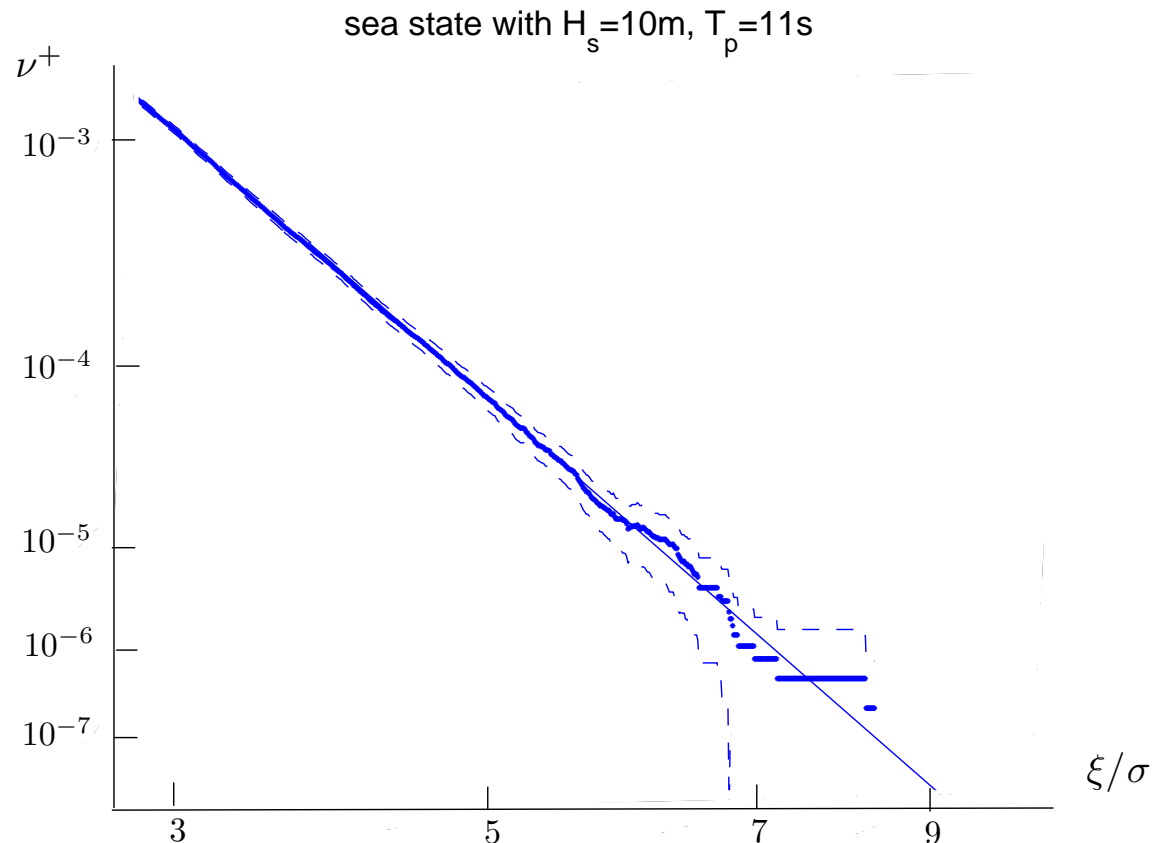
- $\mathbf{F}(t) = \mathbf{F}_1(t) + \mathbf{F}_2(t)$

- A simplified model for the surge response is adopted here:

$$\ddot{Z} + 2\omega_e(\zeta_0 + \tilde{c}F_2(t))\dot{Z} + \omega_e^2(Z + \tilde{\varepsilon}Z^3) = \frac{1}{M}(F_1(t) + F_2(t))$$

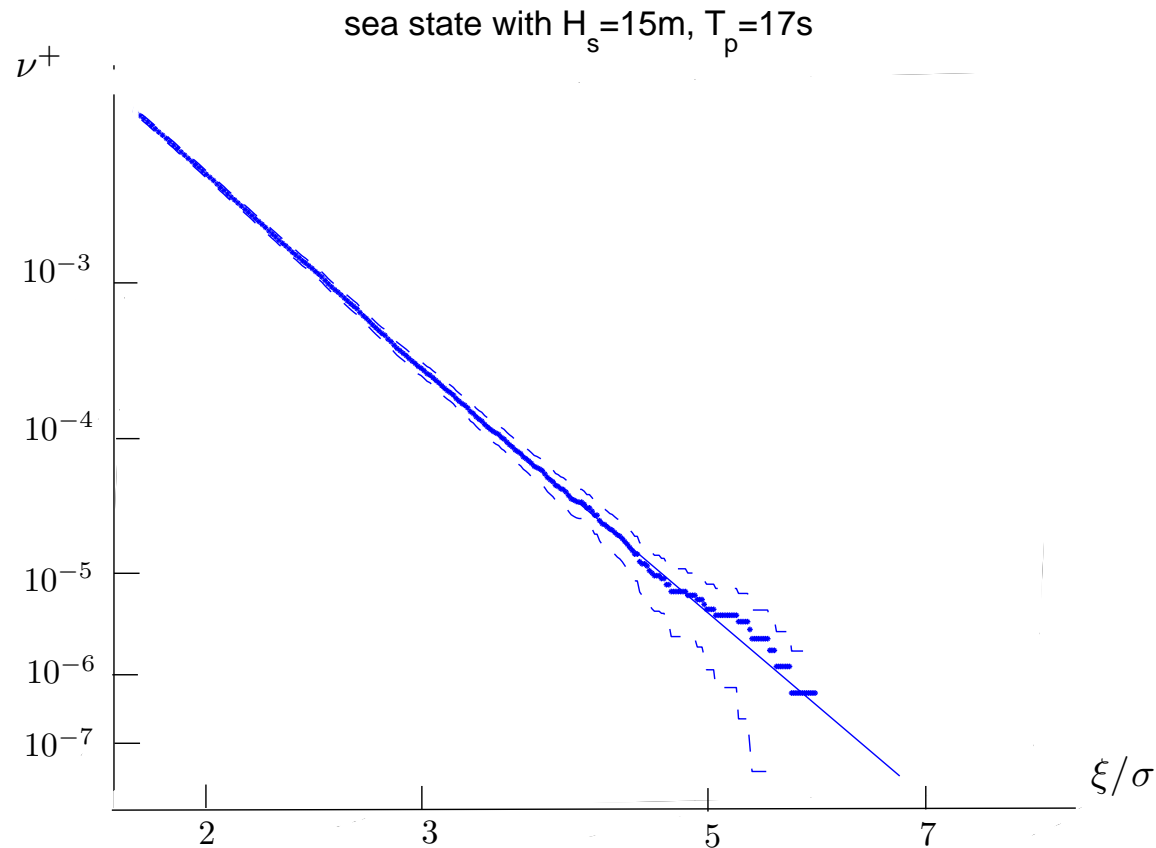
Numerical Examples - TLP

Crossing rates by Monte Carlo simulation (*) with 95% confidence bands (---) and by saddle point integration (—) for the case of linear dynamics ($\tilde{c} = \tilde{\varepsilon} = 0$). Sea state with $H_s = 10$ m, $T_p = 11$ s.



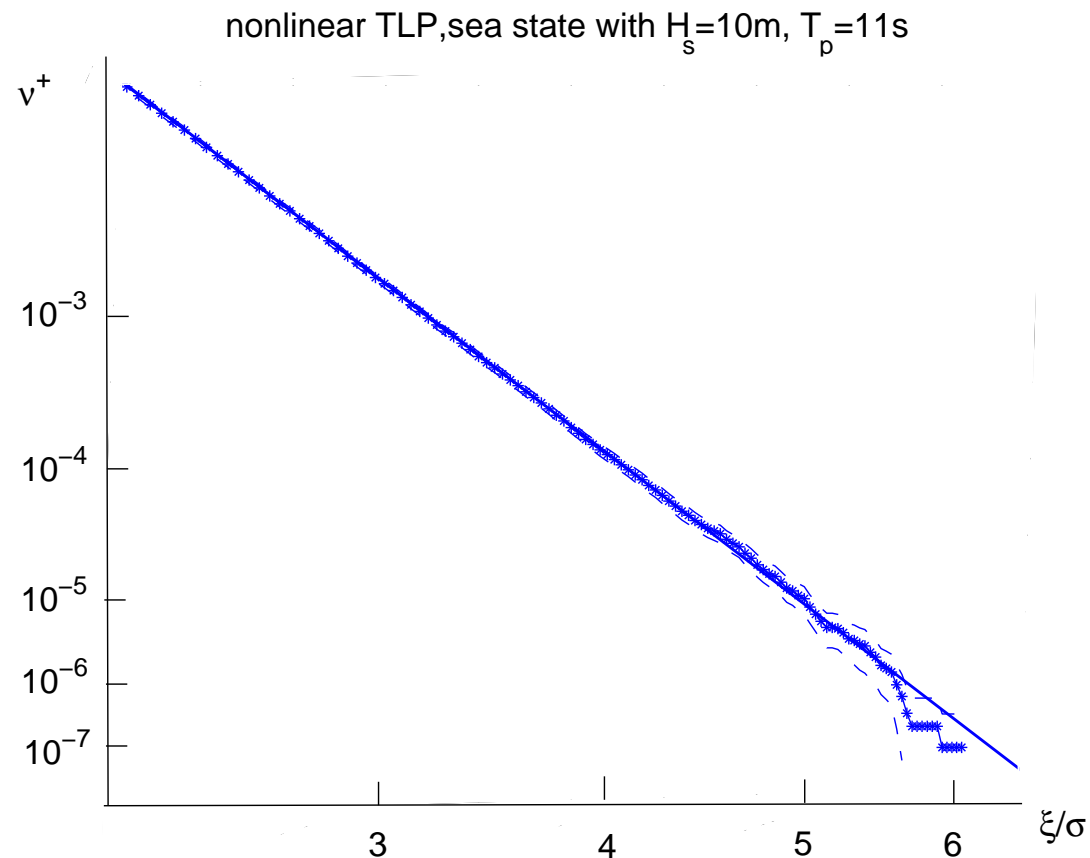
Numerical Examples - TLP

Crossing rates by Monte Carlo simulation (*) with 95% confidence bands (---) and by saddle point integration (—) for the case of linear dynamics ($\tilde{c} = \tilde{\varepsilon} = 0$). Sea state with $H_s = 15$ m, $T_p = 17$ s.



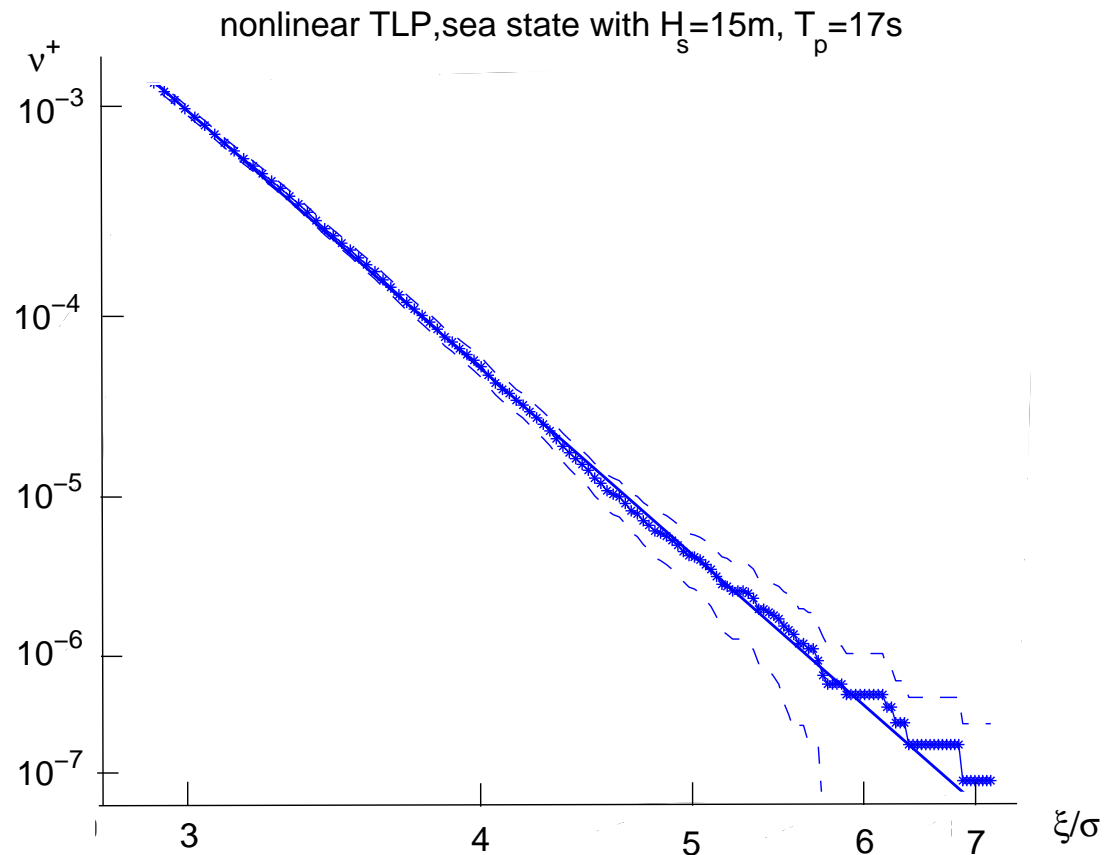
Numerical Examples - TLP

Crossing rates by Monte Carlo simulation (*) with 95% confidence bands (---) for the case of nonlinear dynamics, $q = 0.2$, $b = 5.8 \sigma_Z$.
Sea state with $H_s = 10$ m, $T_p = 11$ s.



Numerical Examples - TLP

Crossing rates by Monte Carlo simulation (*) with 95% confidence bands (---) for the case of nonlinear dynamics, $q = 0.2$, $b = 2.9 \sigma_Z$.
Sea state with $H_s = 15$ m, $T_p = 17$ s.



Conclusions

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- Optimized linear fit and extrapolation on a double logarithmic scale gives accurate predictions of the mean upcrossing rate and thus extreme response statistics.
- The CPU time is in all examples tractable, and it is reduced by a factor of ≥ 100 , compared to straight-forward Monte Carlo simulations down to the same extreme value levels.